

Application-oriented input design for room occupancy estimation algorithms

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The paper in a nutshell

Application-oriented *input design*

for room occupancy estimation algorithms

Why occupancy estimation?

Roadmap

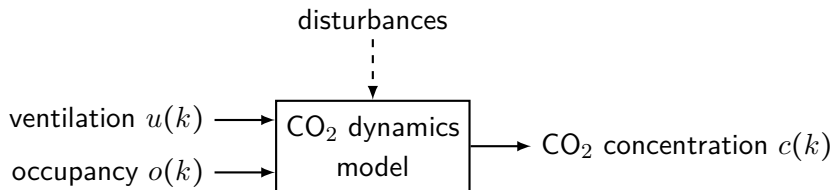
- ① how do we estimate occupancy levels?
- ② how do we identify the system?
- ③ how confident are we in the occupancy estimates?
- ④ can we operate the HVAC so to increase the final confidence on the estimates?
- ⑤ what do we get, in practice?

How do we estimate occupancy levels?

Main idea:

first, identify the dynamics

second, invert the estimation problem



Grey box modelling of the CO₂ dynamics

(Ebadat et al., Multi-room occupancy estimation through adaptive gray-box models, CDC 2015)

Physics-based continuous-time model assuming:

- well-mixed air
- mass conservation

$$v \frac{dc(t)}{dt} = (\dot{Q}^{\text{vent,sup}} + \dot{Q}^{\text{leak,in}})c^{\text{ext}} - (\dot{Q}^{\text{vent,exh}} + \dot{Q}^{\text{leak,out}})c(t) + go(t) \quad (1)$$

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Discretizing and collecting the unknown parameters:

$$\begin{cases} c(k) = \frac{\theta_1}{1 + \theta_3 u(k)} c(k-1) + \frac{\theta_2}{1 + \theta_3 u(k)} o(k) \\ y(k) = c(k) + e(k) \end{cases} \quad (2)$$

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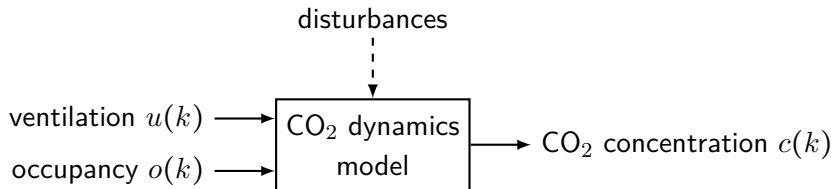
MVU predictor:

$$\widehat{c}(k; \boldsymbol{\theta}, \boldsymbol{o}) = \phi(k, \boldsymbol{o}, \boldsymbol{u}, \boldsymbol{y}, \boldsymbol{\theta}) \quad (3)$$

PEM identification of the CO₂ dynamics

Available information:

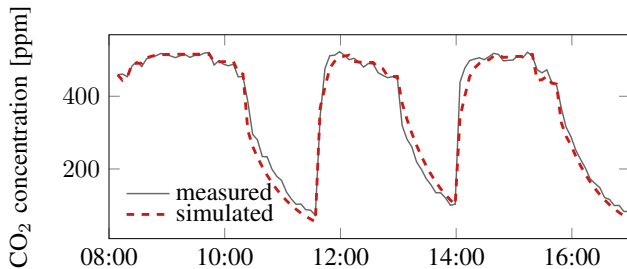
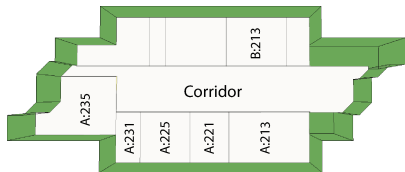
- $o(k)$
- $y(k)$
- $u(k)$



$$\hat{\theta}_N = \arg \min_{\theta \in \Theta} \sum_k \left(y(k) - \hat{c}(k; \theta, \mathbf{o}) \right)^2 \quad (4)$$

How good is this model?

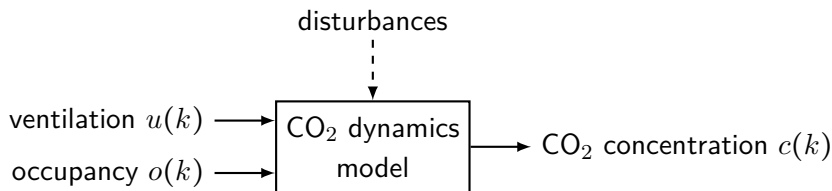
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How to estimate \mathbf{o} given $\widehat{\boldsymbol{\theta}}_N$

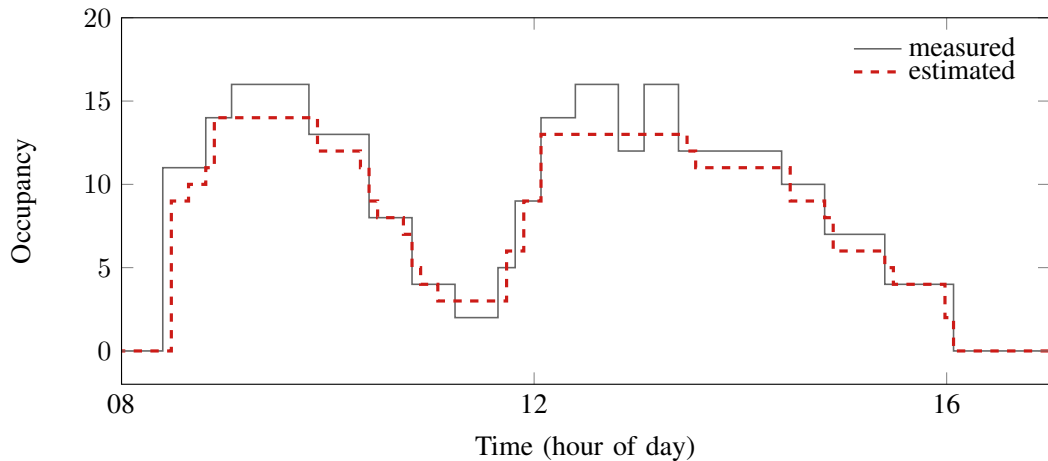
(Ebadat et al., Regularized Deconvolution-based Approaches for Estimating Room Occupancies, T-ASE 2015)

$$\widehat{\mathbf{o}}(\widehat{\boldsymbol{\theta}}_N) = \left[\arg \min_{\tilde{\mathbf{o}}} \sum_{k=1}^N \left(y(k) - \widehat{c}(k; \widehat{\boldsymbol{\theta}}_N, \tilde{\mathbf{o}}) \right)^2 + \lambda \|\Delta \tilde{\mathbf{o}}\|_1 \right] \quad (5)$$



How good is this estimator in practice?

(Ebadat et al., Regularized Deconvolution-based Approaches for Estimating Room Occupancies, T-ASE 2015)



How good is this estimator in theory?

(this paper)

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Cost in terms of occupancy estimation:

$$V_{\text{app}}(\widehat{\boldsymbol{\theta}}_N, \boldsymbol{\theta}_0) := \mathbb{E}_{\mathbf{u}} \left\{ \frac{1}{N} \|\widehat{\boldsymbol{o}}(\widehat{\boldsymbol{\theta}}_N) - \widehat{\boldsymbol{o}}(\boldsymbol{\theta}_0)\|_2^2 \right\} \quad (\text{a.k.a. application function}) \quad (6)$$

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Our requirement:

$$\widehat{\boldsymbol{\theta}}_N \in \Theta_{\text{app}}(\boldsymbol{\theta}_0, \gamma) := \left\{ \boldsymbol{\theta} : V_{\text{app}}(\boldsymbol{\theta}, \boldsymbol{\theta}_0) \leq \gamma^{-1} \right\} \quad (\text{a.k.a. application set}) \quad (7)$$

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Problem: we actually don't know $\boldsymbol{\theta}_0$! \implies substitute it with an initial guess $\widehat{\boldsymbol{\theta}}_0$
(even better, do things recursively)

Our requirement, rephrased

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$$\widehat{\boldsymbol{\theta}}_N \in \Theta_{\text{app}}(\widehat{\boldsymbol{\theta}}_0, \gamma) \quad \rightsquigarrow \quad \lambda_{\min} \left(\widetilde{V}^{-1/2} I_F^N(\widehat{\boldsymbol{\theta}}_0) \widetilde{V}^{-1/2} \right) \geq 1 \quad (9)$$

with

$$\widetilde{V} := \frac{\gamma \chi_\alpha^2(n_{\boldsymbol{\theta}})}{2} \nabla^2 V_{\text{app}}(\widehat{\boldsymbol{\theta}}_0, \widehat{\boldsymbol{\theta}}_0) \quad I_F^N(\widehat{\boldsymbol{\theta}}_0) := \frac{1}{\sigma_e^2} \sum_{k=1}^N \nabla \psi(k, \widehat{\boldsymbol{\theta}}_0)^T \nabla \psi(k, \widehat{\boldsymbol{\theta}}_0) \quad (10)$$

The application-oriented input design problem – in words

$$\begin{aligned} & \underset{\mathbf{u}}{\text{minimize}} && \text{experimental cost} \\ & \text{subject to} && \widehat{\boldsymbol{\theta}}_N \in \Theta_{\text{app}}(\widehat{\boldsymbol{\theta}}_0, \gamma) \\ & && \mathbf{u} \in \text{input constraints} \\ & && \mathbf{y} \in \text{output constraints} \end{aligned} \tag{11}$$

The application-oriented input design problem – in practice

input constraints

final goal of occupancy estimation

= optimize the performance of controllers

= save energy

⇒ use a low-energy ventilation signal during the identification experiment

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Trade-off = constraint

$$\|\mathbf{u}\|_2^2 \leq (1 + \beta) \|\mathbf{u}^*\|_2^2 \quad (12)$$

with

$$\begin{aligned} \mathbf{u}^* = & \operatorname{arg\,min} && \|\mathbf{u}\|_2^2 \\ & \text{subject to} && \mathbf{u} \in \text{hard input constraints} \\ & && \mathbf{y} \in \text{output constraints} \end{aligned} \quad (13)$$

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output constraints

$$\mathbb{P}\{y(k) \leq y_{\max}\} \geq p_y \quad \text{for every } k \quad (14)$$

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Computation through exhaustive search:

$$\mathbb{P}\{y(k) \leq y_{\max}\} = \frac{\sum_{k=1}^{t+N_u} \mathbb{1}(y_{\max} - y(k))}{t + N_u} \quad (15)$$

The application-oriented input design problem – final formulation

$$\begin{aligned} & \underset{\mathbf{u}, N}{\text{minimize}} && N \\ & \text{subject to} && \lambda_{\min} \left(\tilde{\mathbf{V}}^{-1/2} \mathbf{I}_F^N (\hat{\boldsymbol{\theta}}_0) \tilde{\mathbf{V}}^{-1/2} \right) \geq 1 \\ & && \mathbf{u} \in \mathcal{U} \\ & && \|\Delta \mathbf{u}\|_0 \leq n_c \\ & && \|\mathbf{u}\|_2^2 \leq (1 + \beta) \|\mathbf{u}^*\|_2^2 \\ & && \mathbb{P}\{\mathbf{y} \leq y_{\max}\} \geq p_y \end{aligned} \tag{16}$$

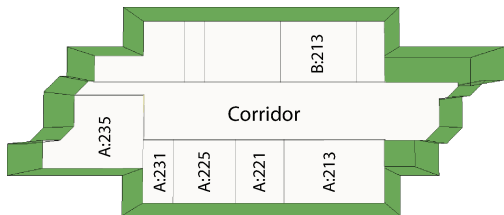
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need: know the groundtruth
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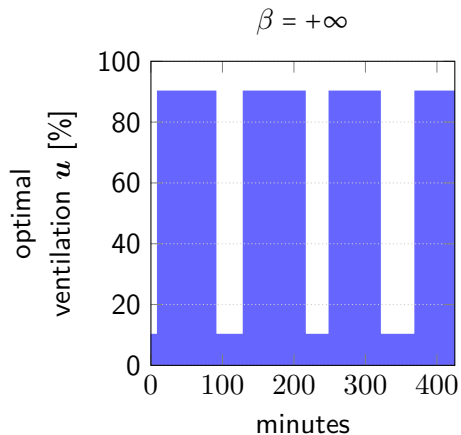
⇒ Monte Carlo on simulated “true” occupancy levels o



EQUA.
IDA Indoor Climate and Energy

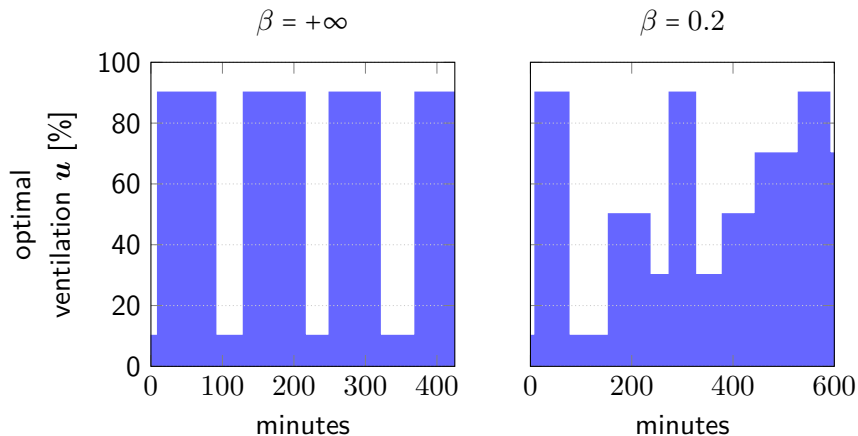
Numerical results – design of the ventilation input u

sampling time = 5 minutes, one single MC run on o

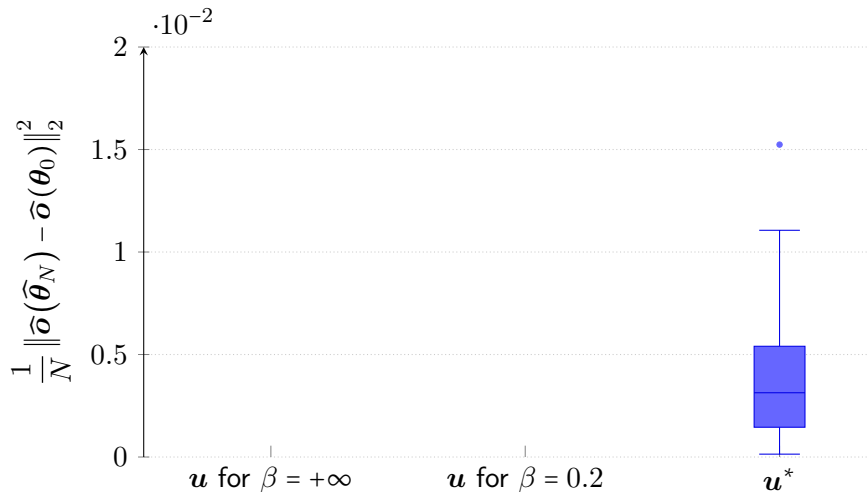


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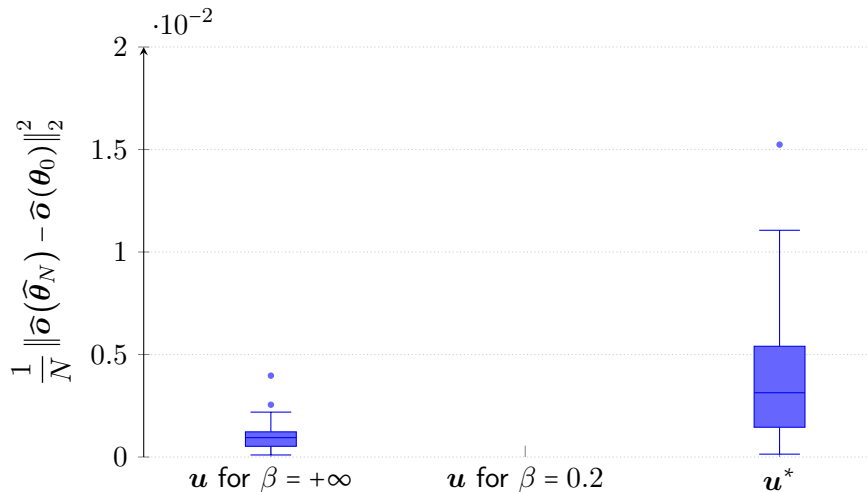
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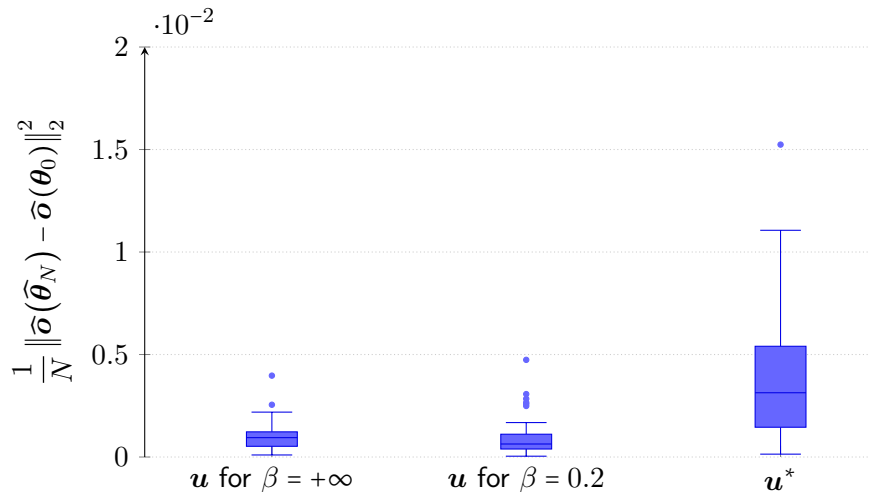
Numerical results – estimation performance on the whole MC on \mathbf{o}



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Problem:

- how well will it work on a real system?

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